

# Package ‘PCpluS’

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**Title** Piecewise Constant Plus Smooth Regression

**Version** 1.0.1

**Depends** R (>= 3.0.2)

**Imports** Rcpp (>= 0.12.3), changepoint, methods, Matrix

**LinkingTo** Rcpp (>= 0.12.3), RcppEigen

**Suggests** testthat (>= 1.0.0), glmnet

**Description** Allows for nonparametric regression where one assumes that the signal is given by the sum of a piecewise constant function and a smooth function. More precisely, it implements the estimator PCpluS (piecewise constant plus smooth regression estimator) from Pein and Shah (2025) <[doi:10.48550/arXiv.2112.03878](https://doi.org/10.48550/arXiv.2112.03878)>.

**License** GPL-3

**NeedsCompilation** yes

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**Repository** CRAN

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cvpcplus	<i>Tuning parameter selection by crossvalidation</i>
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## Description

Selects the tuning parameters, bandwidth and the penalty lambda, of the PCPLUS estimator *F. Pein (2021)*. The values obtained can be used in the estimator [pcplus](#).

**Usage**

```
cv.pcplus(y, bandwidth, lambda, nbandwidth = 30L, nlambda = 30L,
          lambda.min.ratio = 0.01, sd = NULL, thresh = 1e-7, maxit = 1e5L)
```

**Arguments**

<code>y</code>	a numeric vector containing the observations, only finite values are allowed
<code>bandwidth</code>	a numeric vector specifying possible values for the bandwidth of the kernel smoother; each entry must be between $2 / \text{length}(n)$ and $0.25$ or $\text{Inf}$ , smaller values are replaced by $2 / n$ and larger by $\text{Inf}$ with a warning; see <i>F. Pein (2021)</i> for an interpretation of <code>bandwidth == Inf</code> . If missing an exponential grid of length <code>nbandwidth</code> will be used
<code>lambda</code>	a decreasing sequence of numerics specifying possible values for the penalty of the fused lasso; each value must be positive. If missing an exponential grid of length <code>nlambda</code> is used
<code>nbandwidth</code>	a single integer giving the length of the grid for <code>bandwidth</code> ; ignored if <code>bandwidth</code> is given
<code>nlambda</code>	a single integer giving the length of the grid for <code>lambda</code> ; ignored if <code>lambda</code> is given
<code>lambda.min.ratio</code>	a single numeric between $0$ and $1$ specifying the range of the grid for <code>lambda</code> ; ignored if <code>lambda</code> is given. More precisely, for each <code>bandwidth</code> value the largest value of the grid is chosen such that no changes are found and the smallest value is the largest value times <code>lambda.min.ratio</code>
<code>sd</code>	a single positive value giving the standard deviation of the observations; may be <code>NULL</code> , in which case a robust estimator is used
<code>thresh</code>	a single positive numeric value giving a convergence threshold for coordinate descent. Each inner coordinate-descent loop continues until the maximum change in the objective after any coefficient update is less than <code>thresh</code> times the null deviance
<code>maxit</code>	a single positive integer giving the maximum number of passes over the data for all <code>lambda</code> values

**Value**

a `list` containing the entries `lambda` and `bandwidth` giving the best parameter for the tuning parameters. Both can be passed directly to `pcplus`. Note that `lambda` is a decaying sequence instead of a single value. This improves the runtime of the estimator. The last value is the suggested tuning parameter. Furthermore, it has the entries `cv` with the loss for the selected parameters, `bandwidths` with the grid of bandwidths used, and `cvs` with the loss for all bandwidths.

**References**

Pein, F. (2021). Change-point regression with a smooth additive disturbance. *arXiv preprint arXiv:2112.03878*.

**See Also**[pcplus](#)**Examples**

```

library(PCpluS)
set.seed(1)
y <- c(rnorm(125), rnorm(125, 3)) + sin(2 * pi * 1:250 / 250)

CV <- cv.pcplus(y)
ret <- pcplus(y, lambda = CV$lambda, bandwidth = CV$bandwidth)

plot(y, pch = 16)
lines(ret$est, col = "red")
abline(v = ret$cps)

```

pcplus

*Piecewise constant plus smooth estimation***Description**

Computes the PCPLUS estimator *F. Pein (2021)* for a given bandwidth and the penalty lambda. Bandwidth and lambda can be obtained by cross-validation using the function [cv.pcplus](#). The PCPLUS estimator returns a piecewise constant function plus a smooth function as well as the change-points of the piecewise constant function.

**Usage**

```
pcplus(y, bandwidth, lambda, sd = NULL, nlambda = 30L, thresh = 1e-7, maxit = 1e5L)
```

**Arguments**

y	a numeric vector containing the observations, only finite values are allowed
bandwidth	a single positive value specifying the bandwidth for the kernel smoother; must be between $1 / \text{length}(n)$ and $0.25$ or $\text{Inf}$ , smaller values are replaced by $1 / n$ and larger by $\text{Inf}$ with a warning; see <i>F. Pein (2021)</i> for an interpretation of <code>bandwidth == Inf</code>
lambda	a single positive numeric or a decreasing sequence of positive numeric values giving the penalty for the fused lasso. If a sequence is passed, then only the smallest value is used to compute the estimator. However, passing a sequence of lambda values is often much faster than passing a single value
sd	a single positive value giving the standard deviation of the observations; may be NULL, in which case a robust estimator is used
nlambda	a single positive integer specifying the number of lambda values to pass to the lasso; only used if lambda is a single value, in which case an exponentially decreasing sequence is generated, with lambda being the smallest value. As explained for lambda, only this value is used for the estimator, but adding other values may reduce the run time

thresh	a single positive numeric value giving a convergence threshold for coordinate descent. Each inner coordinate-descent loop continues until the maximum change in the objective after any coefficient update is less than thresh times the null deviance
maxit	a single positive integer giving the maximum number of passes over the data for all lambda values

**Value**

a [list](#) containing the entries `est` with the fitted values of the estimator, `smooth` with the smooth part of the estimator, `cpfun` with the change-point part of the estimator, and `cps` with the estimated change-point locations.

**References**

Pein, F. (2021). Change-point regression with a smooth additive disturbance. *arXiv preprint arXiv:2112.03878*.

**See Also**

[cv.pcplus](#)

**Examples**

```
library(PCplus)
set.seed(1)
y <- c(rnorm(125), rnorm(125, 3)) + sin(2 * pi * 1:250 / 250)

CV <- cv.pcplus(y)
ret <- pcplus(y, lambda = CV$lambda, bandwidth = CV$bandwidth)

plot(y, pch = 16)
lines(ret$est, col = "red")
abline(v = ret$cps)
```

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